

Package ‘vntrs’

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Title Variable Neighborhood Trust Region Search

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Description An implementation of the variable neighborhood trust region algorithm Bierlaire et al. (2009) ``A Heuristic for Nonlinear Global Optimization" <[doi:10.1287/ijoc.1090.0343](https://doi.org/10.1287/ijoc.1090.0343)>.

Imports trust

License GPL-3

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check_controls	<i>Check controls.</i>
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Description

This function checks the input controls for the vntrs package.

Usage

```
check_controls(controls)
```

Arguments

controls	<p>Either NULL or a named list with the following elements. Missing elements are set to the default values in parentheses.</p> <ul style="list-style-type: none"> • <code>init_runs</code> (5): The number of initial searches. • <code>init_min</code> (-1): The minimum argument value for the random initialization. • <code>init_max</code> (1): The maximum argument value for the random initialization. • <code>init_iterlim</code> (20): The number of iterations for the initial searches. • <code>neighborhoods</code> (5): The number of nested neighborhoods. • <code>neighbors</code> (5): The number of neighbors in each neighborhood. • <code>beta</code> (0.05): A non-negative weight factor to account for the function's curvature in the selection of the neighbors. If $\beta = 0$, the curvature is ignored. The higher the value, the higher the probability of selecting a neighbor in the direction of the highest function curvature. • <code>iterlim</code> (1000): The maximum number of iterations to be performed before the local search is terminated. • <code>tolerance</code> (1e-6): A positive scalar giving the tolerance for comparing different optimal arguments for equality. • <code>time_limit</code> (NULL): The time limit in seconds for the algorithm.
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Value

The checked and filled list controls.

check_f	<i>Check f.</i>
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Description

This function checks the input f for the vntrs package.

Usage

```
check_f(f, npar, controls)
```

Arguments

f	A function that computes value, gradient, and Hessian of the function to be optimized and returns them as a named list with elements value, gradient, and hessian.
npar	The number of parameters of f.
controls	Either NULL or a named list with the following elements. Missing elements are set to the default values in parentheses. <ul style="list-style-type: none"> • <code>init_runs</code> (5): The number of initial searches. • <code>init_min</code> (-1): The minimum argument value for the random initialization. • <code>init_max</code> (1): The maximum argument value for the random initialization. • <code>init_iterlim</code> (20): The number of iterations for the initial searches. • <code>neighborhoods</code> (5): The number of nested neighborhoods. • <code>neighbors</code> (5): The number of neighbors in each neighborhood. • <code>beta</code> (0.05): A non-negative weight factor to account for the function's curvature in the selection of the neighbors. If $\beta = 0$, the curvature is ignored. The higher the value, the higher the probability of selecting a neighbor in the direction of the highest function curvature. • <code>iterlim</code> (1000): The maximum number of iterations to be performed before the local search is terminated. • <code>tolerance</code> (1e-6): A positive scalar giving the tolerance for comparing different optimal arguments for equality. • <code>time_limit</code> (NULL): The time limit in seconds for the algorithm.

Value

No return value, called for side-effects.

initialize	<i>Initialize VNTRS.</i>
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Description

Function that initializes the variable neighborhood trust region search.

Usage

```
initialize(f, npar, minimize, controls)
```

Arguments

f	A function that computes value, gradient, and Hessian of the function to be optimized and returns them as a named list with elements value, gradient, and hessian.
npar	The number of parameters of f.

minimize	If TRUE, f gets minimized. If FALSE, maximized.
controls	<p>Either NULL or a named list with the following elements. Missing elements are set to the default values in parentheses.</p> <ul style="list-style-type: none"> • <code>init_runs</code> (5): The number of initial searches. • <code>init_min</code> (-1): The minimum argument value for the random initialization. • <code>init_max</code> (1): The maximum argument value for the random initialization. • <code>init_iterlim</code> (20): The number of iterations for the initial searches. • <code>neighborhoods</code> (5): The number of nested neighborhoods. • <code>neighbors</code> (5): The number of neighbors in each neighborhood. • <code>beta</code> (0.05): A non-negative weight factor to account for the function's curvature in the selection of the neighbors. If $\beta = 0$, the curvature is ignored. The higher the value, the higher the probability of selecting a neighbor in the direction of the highest function curvature. • <code>iterlim</code> (1000): The maximum number of iterations to be performed before the local search is terminated. • <code>tolerance</code> (1e-6): A positive scalar giving the tolerance for comparing different optimal arguments for equality. • <code>time_limit</code> (NULL): The time limit in seconds for the algorithm.

Value

A list of

- the list L of identified optima which contains lists with
 - value and
 - argument
 of each identified optimum.
- best initial point x_{best} .

interruption	<i>Interrupt local search.</i>
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Description

This function checks if the local search can be interrupted prematurely.

Usage

```
interruption(f, point, L, minimize)
```

Arguments

f	A function that computes value, gradient, and Hessian of the function to be optimized and returns them as a named list with elements value, gradient, and hessian.
point	The current location of the local search.
L	A list of identified optima which contains lists with <ul style="list-style-type: none"> • value and • argument of each identified optimum.
minimize	If TRUE, f gets minimized. If FALSE, maximized.

Value

TRUE for premature interruption, FALSE if not.

local	<i>Perform trust region local search.</i>
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Description

Function that links to [trust](#).

Usage

```
local(f, parinit, minimize, controls, L)
```

Arguments

f	A function that computes value, gradient, and Hessian of the function to be optimized and returns them as a named list with elements value, gradient, and hessian.
parinit	Passed on to trust .
minimize	If TRUE, f gets minimized. If FALSE, maximized.
controls	Either NULL or a named list with the following elements. Missing elements are set to the default values in parentheses. <ul style="list-style-type: none"> • <code>init_runs</code> (5): The number of initial searches. • <code>init_min</code> (-1): The minimum argument value for the random initialization. • <code>init_max</code> (1): The maximum argument value for the random initialization. • <code>init_iterlim</code> (20): The number of iterations for the initial searches. • <code>neighborhoods</code> (5): The number of nested neighborhoods. • <code>neighbors</code> (5): The number of neighbors in each neighborhood.

- `beta (0.05)`: A non-negative weight factor to account for the function's curvature in the selection of the neighbors. If `beta = 0`, the curvature is ignored. The higher the value, the higher the probability of selecting a neighbor in the direction of the highest function curvature.
- `iterlim (1000)`: The maximum number of iterations to be performed before the local search is terminated.
- `tolerance (1e-6)`: A positive scalar giving the tolerance for comparing different optimal arguments for equality.
- `time_limit (NULL)`: The time limit in seconds for the algorithm.

L A list of identified optima which contains lists with

- `value` and
- `argument`

of each identified optimum.

Value

A list of

- `success`: A boolean, determining whether the local search successfully converged.
- `value`: The value at the point where the local search terminated.
- `argument`: The point where the local search terminated.

<code>select_neighbors</code>	<i>Select neighbors.</i>
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Description

Function that selects neighbors around a given point `x`.

Usage

```
select_neighbors(f, x, neighborhood_expansion, controls)
```

Arguments

<code>f</code>	A function that computes value, gradient, and Hessian of the function to be optimized and returns them as a named list with elements <code>value</code> , <code>gradient</code> , and <code>hessian</code> .
<code>x</code>	A point in the domain of <code>f</code> .
<code>neighborhood_expansion</code>	A scaling factor, specifying the expansion of the neighborhood.
<code>controls</code>	Either <code>NULL</code> or a named list with the following elements. Missing elements are set to the default values in parentheses. <ul style="list-style-type: none"> • <code>init_runs (5)</code>: The number of initial searches.

- `init_min` (-1): The minimum argument value for the random initialization.
- `init_max` (1): The maximum argument value for the random initialization.
- `init_iterlim` (20): The number of iterations for the initial searches.
- `neighborhoods` (5): The number of nested neighborhoods.
- `neighbors` (5): The number of neighbors in each neighborhood.
- `beta` (0.05): A non-negative weight factor to account for the function's curvature in the selection of the neighbors. If `beta = 0`, the curvature is ignored. The higher the value, the higher the probability of selecting a neighbor in the direction of the highest function curvature.
- `iterlim` (1000): The maximum number of iterations to be performed before the local search is terminated.
- `tolerance` (1e-6): A positive scalar giving the tolerance for comparing different optimal arguments for equality.
- `time_limit` (NULL): The time limit in seconds for the algorithm.

Value

A list points in the domain of `f` which neighbors of `x`.

<code>unique_optimum</code>	<i>Check new optimum for uniqueness.</i>
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Description

This function checks if a new optimum argument is not yet contained in `L`.

Usage

```
unique_optimum(L, argument, tolerance)
```

Arguments

<code>L</code>	A list of identified optima which contains lists with <ul style="list-style-type: none"> • <code>value</code> and • <code>argument</code> of each identified optimum.
<code>argument</code>	The argument of a candidate optimum.
<code>tolerance</code>	A non-negative numeric value. For an identified optimum and a candidate optimum, if all coordinate differences are smaller than <code>tolerance</code> , they are considered as equal.

Value

A boolean. If `TRUE`, `argument` is not contained in `L`. If `FALSE`, `argument` is already contained in `L`.

vntrs	<i>Variable neighborhood trust region search.</i>
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Description

This function performs variable neighborhood trust region search.

Usage

```
vntrs(f, npar, minimize = TRUE, controls = NULL, quiet = TRUE, seed = NULL)
```

Arguments

f	A function that computes value, gradient, and Hessian of the function to be optimized and returns them as a named list with elements value, gradient, and hessian.
npar	The number of parameters of f.
minimize	If TRUE, f gets minimized. If FALSE, maximized.
controls	<p>Either NULL or a named list with the following elements. Missing elements are set to the default values in parentheses.</p> <ul style="list-style-type: none"> • <code>init_runs</code> (5): The number of initial searches. • <code>init_min</code> (-1): The minimum argument value for the random initialization. • <code>init_max</code> (1): The maximum argument value for the random initialization. • <code>init_iterlim</code> (20): The number of iterations for the initial searches. • <code>neighborhoods</code> (5): The number of nested neighborhoods. • <code>neighbors</code> (5): The number of neighbors in each neighborhood. • <code>beta</code> (0.05): A non-negative weight factor to account for the function's curvature in the selection of the neighbors. If <code>beta = 0</code>, the curvature is ignored. The higher the value, the higher the probability of selecting a neighbor in the direction of the highest function curvature. • <code>iterlim</code> (1000): The maximum number of iterations to be performed before the local search is terminated. • <code>tolerance</code> (1e-6): A positive scalar giving the tolerance for comparing different optimal arguments for equality. • <code>time_limit</code> (NULL): The time limit in seconds for the algorithm.
quiet	If TRUE, progress messages are suppressed.
seed	Set a seed for the sampling of the random starting points.

Value

A data frame. Each row contains information of an identified optimum. The first `npar` columns "p1", ..., "p<npar>" store the argument values, the next column "value" has the optimal function values and the last column "global" contains TRUE for global optima and FALSE for local optima.

References

Bierlaire et al. (2009) "A Heuristic for Nonlinear Global Optimization" doi: [10.1287/ijoc.1090.0343](https://doi.org/10.1287/ijoc.1090.0343).

Examples

```
rosenbrock = function(x) {
  stopifnot(is.numeric(x))
  stopifnot(length(x) == 2)
  f = expression(100 * (x2 - x1^2)^2 + (1 - x1)^2)
  g1 = D(f, "x1")
  g2 = D(f, "x2")
  h11 = D(g1, "x1")
  h12 = D(g1, "x2")
  h22 = D(g2, "x2")
  x1 = x[1]
  x2 = x[2]
  f = eval(f)
  g = c(eval(g1), eval(g2))
  h = rbind(c(eval(h11), eval(h12)), c(eval(h12), eval(h22)))
  list(value = f, gradient = g, hessian = h)
}
vntrs(f = rosenbrock, npar = 2, seed = 1, controls = list(neighborhoods = 1))
```

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